



Replacing the Real-Time Clock (RTC) battery in a 62xx system

To replace the RTC battery in the controller module, you must perform a specific sequence of steps.

About this task

- You can use this procedure with all versions of Data ONTAP supported by your system.
In this procedure, a *Cluster-Mode system* refers to a system running Data ONTAP 8.x Cluster-Mode. A *7-Mode system* refers to a system running Data ONTAP 8.x 7-Mode or releases prior to Data ONTAP 8.0.
 - This procedure refers to *HA pairs*, which in releases prior to Data ONTAP 8.0 were called *active/active configurations*.
 - All other components in the system must be functioning properly; if not, you must contact technical support.
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Shutting down the node

You shut down a node using different procedures, depending on whether it is a stand-alone system or part of an HA pair.

Next topics

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Shutting down a node in an HA pair

To shut down the node, you must determine the status of the node and, if necessary, take over the node so that the partner continues to serve data from the node's storage.

About this task

As part of this procedure, you leave the power supplies or turn them off depending on your configuration:

- If you have two controller modules in the same chassis, you must leave the power supplies turned on to provide power to the partner node.
- If you have one controller module in the chassis, but is part of an HA pair, you should turn off the power supplies in the target node chassis.

Steps

1. Check the status of the target node (the node you want to perform maintenance on) by entering the following command at the system console of either node:



If your system is configured in...	Then issue this command...
7-Mode	<code>cf status</code>
Cluster-Mode	<code>storage failover show</code>

- Take one of the following actions, depending on the result of the `cf status` or `storage failover show` command:

If...	Then...
Neither node is in takeover mode	Go to the next step in this procedure.
The partner node took over the target node	The target node is in a state where you can begin removing it from the system chassis.
The target node took over the partner node	<ol style="list-style-type: none"> Correct the problem that caused the takeover. Run the <code>cf giveback</code> command (if in a 7-Mode system) or <code>storage failover giveback</code> command (if in a Cluster-Mode system) from the target node console. Go back to the beginning of this procedure.

- Take over the target node by entering one of the following commands from the partner node's console:

If your system is configured in...	Then issue this command...
7-Mode	<code>cf takeover</code>
Cluster-Mode	<code>storage failover takeover -bynode node</code>

- Take one of the following actions depending on your system configuration:

If your system has...	Then...
Two controller modules in the chassis	Do not shut off the power supplies.
One controller module in the chassis	Turn off the power supplies and unplug them from the power sources.

Shutting down the node in a stand-alone system

For a node that is in a stand-alone configuration, you must perform a clean shutdown (ensuring that all data has been written to disk) and disconnect the power supplies.

Steps

- Enter one of the following commands from the system console:

If your system is configured in...	Then issue this command...
7-Mode	<code>halt</code>
Cluster-Mode	<code>halt local</code>

- If you are not already grounded, properly ground yourself.
- Turn off the power supplies, unplug both power cords from the power source, and then remove the power cords.

Opening the system

To access components inside the controller module, you must open the system.

Steps

1. If you are not already grounded, properly ground yourself.
2. Unplug the system cables from the controller module, as needed, and keep track of where the cables were connected.
Leave the cables in the cable management tray so that when you reinstall the cable management tray in the controller module, the cables will be organized.
3. Grasp the cable management tray by the side, gently push one side of the tray so that the arm slides across and off the retaining pin, slide the other arm off the retaining pin on the other side of the controller module, and then lift it off the back of the controller module and set it aside.
4. Loosen the thumbscrew on the cam handle.
5. Pull the cam handle downward and slide the controller module out of the system until it catches.
6. Push in the release latch on the left side of the controller module and slide the controller module out of the system and set it on a stable, antistatic surface.

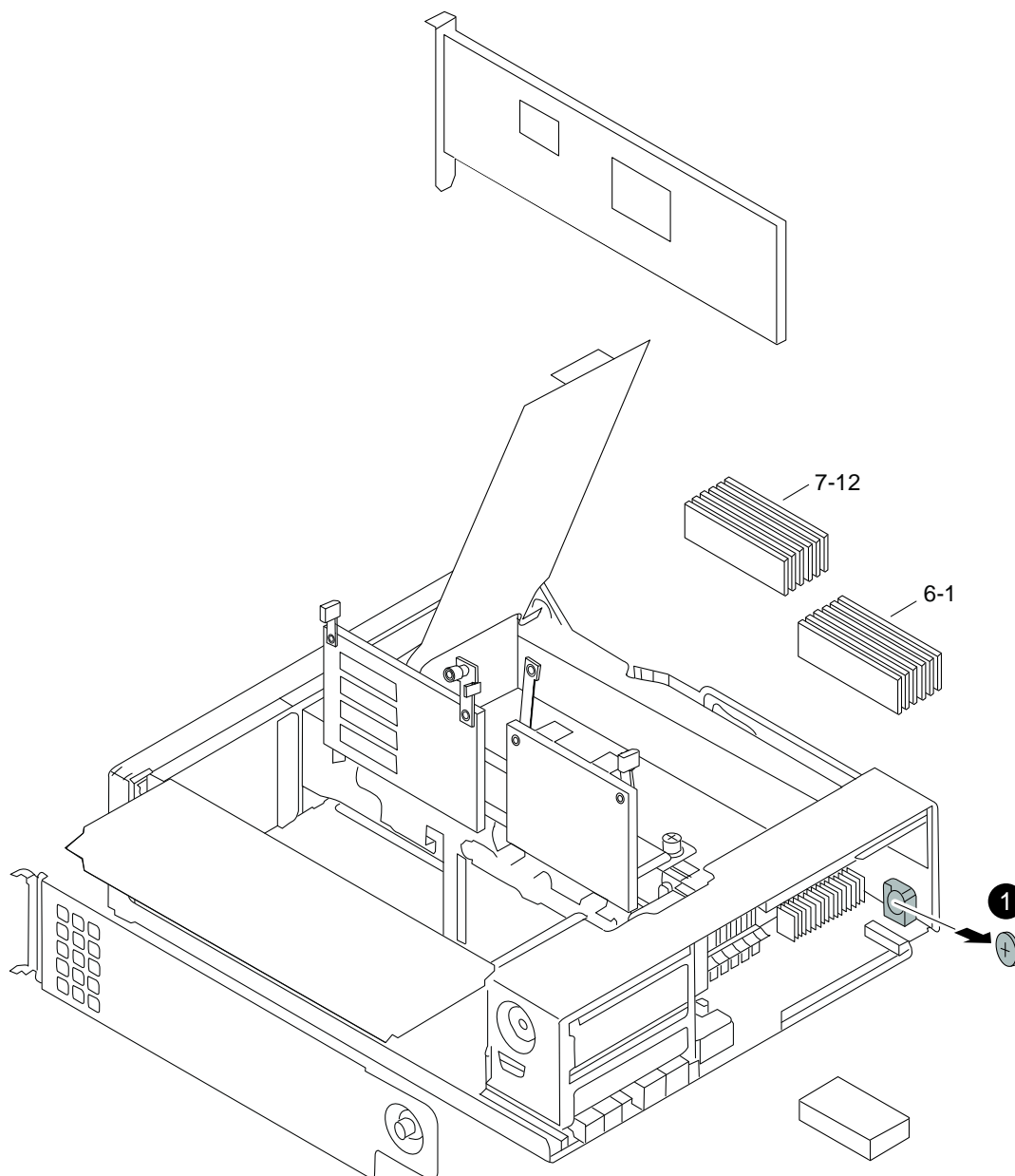
Make sure that you support the bottom of the controller module with your free hand.

Removing an RTC battery

You must follow a specific sequence of steps to remove the RTC battery from the controller module.

Steps

1. Locate the RTC battery on the right side and at the back of the controller module as you slide the controller module out of the chassis.



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RTC battery and holder

2. Place your thumb or forefinger on the battery, gently push the battery down, rotate it away from the holder, and then lift the battery out of the holder.

Note: Note the polarity of the battery as you remove it from the holder.

Installing an RTC battery

You must follow a specific sequence of steps to install a Real-Time Clock (RTC) battery.

Steps

1. If you are not already grounded, properly ground yourself.

2. Remove the replacement battery from the antistatic shipping bag.
3. Locate the empty battery holder in the controller module and insert the battery into the holder by placing your finger on the top of the RTC battery and gently pushing down, while pulling the top part of the battery away from the side of the chassis..
The battery should easily slide into the battery holder. If it does not, turn the battery over and reinstall it.
4. Visually inspect the battery to make sure that it is completely installed into the holder and that the polarity is correct.
There is a large “+” on the motherboard indicating battery polarity.

Reinstalling the controller module and booting the system

After you replace a component within the controller module, you must reinstall the controller module in the system chassis and boot it to a state where you can run diagnostic tests on the replaced component.

About this task

Note: For HA pairs with two controller modules in the same chassis, the sequence in which you reinstall the controller module is especially important because it attempts to reboot as soon as you completely seat it in the chassis.

Steps

1. Align the end of the controller module with the opening in the chassis, if necessary, and then gently push the controller module halfway into the system.
2. Reinstall the cable management arms and recable the controller module, as needed.
When recabling, remember to reinstall the media converters (SFPs) if you are using fiber cables.
3. Reinstall the controller module:
 - a. Push the controller module all the way into the system.
 - b. Push the cam handle to finish seating the controller module.
 - c. Close the cam and tighten the thumbscrew.
 - d. Halt the boot process.
 - For systems in an HA pair, press Ctrl-c.
 - For stand-alone systems, reconnect the power cables to the power supplies and to the power sources, turn on the power to start the boot process, and then press Ctrl-c.

The boot process is halted at either the Boot menu or the Loader prompt.

Running diagnostics on the RTC battery

After installing the RTC battery, you should run diagnostics.

Steps

1. Complete the applicable step, depending on where the node halted during the boot process.

If the node halted at the...	Then...
Loader prompt	Continue with the procedure.

If the node halted at the...	Then...
Boot menu	<ol style="list-style-type: none"> Select the Maintenance mode option from the displayed menu. Enter the following command at the prompt: halt Continue with the procedure.

- Enter the following command at the Loader prompt:

```
boot_diags
```

Note: You must run this command from the Loader prompt for system-level diagnostics to function properly. The `boot_diags` command starts special drivers designed specifically for system-level diagnostics.

The Maintenance mode prompt (`*>`) appears.

- Enter the following command at the Maintenance mode prompt:

```
sldiag
```

For details about the `sldiag` command, see the `sldiag` man page.

- Clear the status logs by entering the following command:

```
sldiag device clearstatus
```

- Verify that the log is cleared by entering the following command:

```
sldiag device status
```

The following default response is displayed:

```
SLDIAG: No log messages are present.
```

- Run the sensor-related environmental tests for the RTC battery by entering the following command from the Maintenance mode prompt:

```
sldiag device run -dev env
```

Note: See the *System-Level Diagnostics Guide* for a description of the types of tests you can run.

- View the status of the test by entering the following command:

```
sldiag device status
```

Your storage system provides the following output while the tests are still running:

```
There are still test(s) being processed.
```

After all the tests are complete, the following response appears by default:

```
*> <SLDIAG: _ALL_TESTS_COMPLETED>
```

- Verify that no hardware problems resulted from the addition or replacement of hardware components on your system by entering the following command:

```
sldiag device status [-dev devtype] [-name device] -long -state failed
```

System-level diagnostics returns you to the prompt if there are no test failures, or lists the full status of failures resulting from testing the component.

- Proceed based on the result of the preceding step.

If the system-level diagnostics tests...	Then...
Were completed without any failures	<ol style="list-style-type: none"> Clear the status logs by entering the following command: sldiag device clearstatus Verify that the log is cleared by entering the following command: sldiag device status The following default response is displayed: <pre>SLDIAG: No log messages are present.</pre> Exit Maintenance mode by entering the following command: halt Enter the following command at the firmware prompt to reboot the storage system: boot If your system is in an HA pair, run the <code>cf giveback</code> command (if in a 7-Mode system) or <code>storage failover giveback</code> command (if in a Cluster-Mode system) from the partner node console. <p>You have completed system-level diagnostics.</p>
Resulted in some test failures	<p>Determine the cause of the problem.</p> <ol style="list-style-type: none"> Exit Maintenance mode by entering the following command: halt Perform a clean shutdown and disconnect the power supplies. Verify that you have observed all the considerations identified for running system-level diagnostics, that cables are securely connected, and that hardware components are properly installed in the storage system. Reconnect the power supplies and power on the storage system. Rerun the system-level diagnostics tests.

Related information

System-Level Diagnostics Guide: now.netapp.com/NOW/knowledge/docs/hardware/NetApp/diag/sldiag.pdf

Resetting the date and time on the system

After you reconnect the battery and reboot Data ONTAP, you must check the date and time on the system and reset them if the RTC battery was dead or has been out of the system for more than 10 minutes.

Steps

1. Display the current date on the node or nodes by entering the following command:

If you have a...	Then issue this command...
7-Mode system	date Note: If your system is in an HA pair, make sure that you display the date and time on the partner node and set the target node to those values.
Cluster-Mode system	system date show Note: Make sure that you display the date and time on the other nodes in the cluster and set the target node to those values.

2. Set the date by entering the following command:

If you have a...	Then issue this command...
7-Mode system	<pre>date [-u] [[CC]yy]mmddhhmm>[.<ss>]]</pre> <p>-u sets the date and time to Greenwich Mean Time instead of the local time.</p> <p>CC is the first two digits of the current year.</p> <p>yy is the second two digits of the current year.</p> <p>mm is the current month. If the month is omitted, the default is the current month.</p> <p>dd is the current day. If the day is omitted, the default is the current day.</p> <p>hh is the current hour, using a 24-hour clock.</p> <p>mm is the current minute.</p> <p>ss is the current second. If the seconds are omitted, the default is 0.</p>
Cluster-Mode system	<pre>system date modify -node node_name -date date_and_time</pre> <p>node_name is the target node.</p> <p>date_and_time is the date and time setting for the node, in the format MM/DD/YYYY HH:MM:SS.</p>

Note: The *Data ONTAP 7-Mode System Administration Guide* or the *Data ONTAP Cluster-Mode System Administration Guide* contains more information about setting the system date and time.

Example

The following command sets the date and time to 22 May 2009 at 9:25 a.m. on a 7-Mode system:

```
date 200905220925
```

Example

The following command sets the date and time to 22 May 2009 at 9:25 a.m. on a Cluster-Mode system:

```
system date modify -node system1 -date "05/22/2009 09:25:00"
```

Related information

[Data ONTAP Information Library: now.netapp.com/NOW/knowledge/docs/ontap/ontap_index.shtml](http://now.netapp.com/NOW/knowledge/docs/ontap/ontap_index.shtml)

Completing the replacement process

After you replace the part, you can return the failed part to NetApp, as described in the RMA instructions shipped with the kit. Contact NetApp technical support at 888-463-8277 (North America), 00-800-44-NETAPP (Europe), or +800-800-80-800 (Asia/Pacific) if you need the RMA number or additional help with the replacement procedure.

Disposing of batteries

Dispose of batteries according to local regulations regarding battery recycling or disposal. If you cannot properly dispose of the battery, return it to NetApp, as described in the RMA instructions shipped with the kit.

Related information

[Warranty Agreement, Safety Information, and Regulatory Notices: now.netapp.com/NOW/knowledge/docs/hardware/hardware_index.shtml](http://now.netapp.com/NOW/knowledge/docs/hardware/hardware_index.shtml)

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